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A Lattice based Nearest Neighbor Classifier for Anomaly Intrusion Detection

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Abstract

As networking and communication technology becomes more widespread, the quantity and impact of system attackers have been increased rapidly. The methodology of intrusion detection (IDS) is generally classified into two broad categories according to the detection approaches: misuse detection and anomaly detection. In misuse detection approach, abnormal system behavior is defined at first, and then any other behavior is defined as normal behavior. The main goal of the anomaly detection approach is to construct a model representing normal activities. Then, any deviation from this model can be considered as an anomaly, and recognized to be an attack. Recently much more attention is paid to the application of lattice theory in different fields. In this work we propose a lattice based nearest neighbor classifier capable of distinguishing between bad connections, called attacks, and good normal connections. A new nonlinear valuation function is introduced to tune the performance of the proposed model. The performance of the algorithm was evaluated by using KDD Cup 99 Data Set, the benchmark dataset used by Intrusion detection Systems researchers. Simulation results confirm the effectiveness of the proposed method.

Keywords: Anomaly detection, Nearest Neighbor, Lattice Theory, Positive Valuation Function, KDD Cup 99

1. Introduction

As networking and communication technology becomes more widespread, the quantity and impact of spammers, system attackers, and criminal enterprises have been increased rapidly. The research in this area has mainly focused on the development of system security mechanisms like firewalls. However, as complete prevention of computer attacks is not possible, many researchers have concentrated their effort on developing novel detection techniques, capable of promptly identifying network attacks. IDS is used to detect any intruder which might have entered into the computers or networks. The methodology of intrusion detection is generally classified into two broad categories according to the detection approaches: misuse detection and anomaly detection. The misuse detection approach (also called signature based detection) [1],[2],[3] is based on extensive knowledge of patterns associated with known attacks or signatures so that even variations of these attacks can be detected. Based on these

signatures, this approach detects attacks through a large set of rules describing every known attack. Signature based intrusion detection systems rely on human intervention to create, test, and deploy the signatures. Thus, it may take hours or days to generate a new signature for an attack which can be too long when dealing with rapidly moving attacks, such as worm propagation. Some effort has been put into automatic signature generation, which does not require human intervention, but these systems are not yet ready for large scale deployment [4]. Although misuse detection systems have the capability of detecting many or all known attack patterns but they are unable to detect novel and unanticipated attacks. The main goal of the anomaly detection (also called profile based detection) approach [5-8] is to construct a model representing normal activities. Then, any deviation from this model can be considered as an anomaly, and recognized to be an attack. Notice that when this approach is employed, it is possible to recognize unforeseen attacks, although in some cases, this approach can lead to a high false attack rate. Due to this potentiality of detecting unknown attacks there has been a fast growing interest in developing new techniques to build models based on normal traffic behavior in the past years.

Profiles of normal behavior can be built with a variety of techniques including statistical methods [9],[10],[11],[12], association rules [13],[14], neural networks [15], computer immunology [16], and specification based methods [17].

At the early stage, the research focus lies in using rule-based expert systems and statistical approaches. But when encountering larger datasets, the results of rule-based expert systems and statistical approaches become worse. Thus, many data mining techniques have been introduced to solve the problem. Among these techniques, the Artificial Neural Network (ANN) is widely used and has been successful in solving many complex practical problems [18].

ANNs have been proposed as alternatives to the statistical analysis component of anomaly detection systems [19],[20]. Brause et al. [21] used a compound method based on rule-based systems and an ANN for credit card fraud detection. Other ANN based credit card fraud detection systems have been undertaken by Hassibi [22], Dorronsoro et al. [23] and Syeda et al. [24]. Wang et al. [20] proposed a new approach called FC-ANN based on ANN and fuzzy clustering to solve the problem and help IDS to achieve a higher detection rate. In [25],[26] SVM was proposed as an approach for novelty detection with a significant success rate. Unfortunately, as noticed by Eskin et al. [27], SVM for novelty detection works under the assumption that the number of normal traffic instances vastly outnumbers the number of anomalies.

Lattice computing is an interesting topic which has been taken into account by several authors. The term lattice computing was introduced recently by Graña [28]. More specifically, lattice computing was defined as the class of algorithms that uses lattice theory either to achieve pattern recognition or to produce generalizations. Lattices are popular in mathematical morphology including image processing applications [29,30]. Moreover, algebraic lattices have been used for modeling associative memories [31]. One way and bidirectional lattice associative memories [32] have been proposed to overcome capacity limitations [33],[34]. Lattices are used implicitly in some neural networks such as fuzzy-ART and min-max [35],[36]. Petridis and Kaburlasos [37] have found inspiration in lattice theory and versions of the ART model and have devised another successful approach to lattice-based computational

intelligence. Moreover, in [38] a fuzzy interval number k-nearest neighbor classifier has been proposed and was successfully applied to predicting annual sugar production.

This paper presents a novel nearest neighbor classification algorithm for the anomaly intrusion detection based on lattice theory. A practical advantage of lattice theory is the ability to model both uncertain information and disparate types of lattice-ordered data [39]. Indeed, our proposed algorithm is capable of dealing with disparate type of data including real vectors, fuzzy sets, symbols, graphs, images, waves and even any combination of the aforementioned data. It can handle both points and intervals. Learning in the proposed algorithm is carried out fast therefore, in many application, when the data is so massive, and the analysis process so time consuming, the proposed algorithm can be a proper choice.

The layout of this paper is as follows. In Section 2 the mathematical background on lattices is reviewed. Section 3 explains our proposed model. Section 4 provides empirical results that demonstrate the performance of our proposed model. Finally, Section 5 summarizes the results of this work.

2. Mathematical Background

A lattice (L, \leq) is a partially ordered set (or, simply, poset) such that any two of its elements $a, b \in L$ have a greatest lower bound $ab = inf\{a, b\}$ and a least upper bound $ab = sup\{a, b\}$. The lattice operations A and \vee ware also called meet and join, respectively. A lattice (L, \leq) is called complete when each of its subsets has a least upper bound and a greatest lower bound in L [40]. A non-void complete lattice has a least element and a greatest element denoted by O and I, respectively. The inverse $\geq \geq$ of an order relation \leq is itself an order relation. The order \geq is called the *dual* order of \leq , symbolically \leq^{∂} . A lattice (L, \leq) can be Cartesian product of N constituent lattices $L_1, ..., L_N$ i.e. $L = L_1 \times \cdots \times L_N$. The lattice operations meet and join of product lattice are defined as below:

$$a \wedge b = (a_1, \dots, a_N) \wedge (b_1, \dots, b_N) = (a_1 \wedge b_1, \dots, a_N \wedge b_N)$$
(1)

$$a \lor b = (a_1, \dots, a_N) \lor (b_1, \dots, b_N) = (a_1 \lor b_1, \dots, a_N \lor b_N)$$
 (2)

A valuation on a crisp lattice L is a real-valued function $v: L \to R$ which satisfies $v(a) + v(b) = v(a \lor b) - v(a \land b)$, $a, b \in L$. A valuation is called monotone iff $a \le b$ in L implies $v(a) \le v(b)$ and positive iff a < b implies v(a) < v(b).

Consider the set R of real numbers. It turns out that $(\overline{R} = R \cup \{-\infty, +\infty\}, \le)$ under the inequality relation \le between $a, b \in R$ is a complete lattice with the least element $-\infty$ and the greatest element $+\infty$ [41]. A lattice (L, \le) is totally ordered if and only if for any $a, b \in L$ either $a \ge b$ or a < b. The lattices (\overline{R}^N, \le) and $([0,1]^N, \le)$ under inequality relation are not a totally ordered lattice.

We remark that the goal of positive valuation function v is to deal with lattice elements. Choosing a suitable valuation function is problem dependent. Various positive valuation function have been proposed in the literature [42],[43],[44]. In our experiments the data have been normalized in lattice $L=[0,1]^N$, the unit N dimensional hypercube, by the function $x_{Norm} = \frac{X - X_{min}}{X_{max} - X_{min}}$ where, x_{min} and x_{max} stands for respectively the least and greatest attribute values of the data and N is the dimension of the input data. Thus, we propose the following nonlinear positive valuation function.

For all
$$A \in ([0,1]^N, \leq)$$
, $v(A) = \sum_{i=1}^N \sin(a_i)$ (3)

Based on the principle that for $\forall a \in [0,1]$, $a \leq \sin(a)$, it can be easily proved that $v(A \lor B) + v(A \land B) = v(A) + v(B)$, $A, B \in [0,1]^N$. Furthermore, Figure 1. Shows that the proposed valuation function is a strictly increasing function in lattice $L = [0,1]^N$. Finally the aforementioned function (3) maps the least element of lattice $([0,1]^N, \leq)$ to zero. Thus, it satisfies the conditions of a positive valuation function.



Figure 1. The positive valuation function y=sin(x).

In some applications, we may want to numerically express the differences of two objects by means of the distance of the corresponding sets. It follows that if two sets A and B have a large similarity, then they will have a small distance. A formal definition of metric distance is given in [45]. Here we introduce a useful metric distance function capable to deal with lattice elements. For two N-dimensional vectors $A = (a_1, ..., a_N)$ and $B = (b_1, ..., b_N)$ the following metric distance $d: L \times L \rightarrow [0,1]$ in a lattice L is defined as follows:

$$d(A, B) = v(A \lor b) - v(A \land B) = \sum_{i=1}^{N} [v(a_i \lor b_i) - v(a_i \land b_i)].$$

For more details, we refer the reader to [40,42].

3. The proposed model

This section presents a nearest neighbor classifier based on lattice theory capable of detecting large-scale attacks in real-time. The nearest neighbor classifier assigns to a test sample a class label of its closest neighbor using a metric distance such as Euclidean distance typically used in conventional nearest neighbor. Our proposed

Classifier uses the metric distance introduced in the previous section to compute the distance of a given test sample with a predefined normal profile. If the distance is less than a user defined threshold then the test pattern will be labeled as "normal" situation otherwise a network intrusion is reported. One of its important properties is the ability of dealing with disparate type of data including real vectors, fuzzy sets, symbols, graphs, images, waves and even any combination of the aforementioned data and this shows the ability of the algorithm in combining different type of data. Furthermore, the proposed model can cope with both points and intervals. The inherent speed of the algorithm for training, detecting attacks timely and having a simple structure to implement are other benefits of this approach. The algorithm is described in the following:

The proposed algorithm

so. sel	lect a 1	new da	atum P	as a	normal	profile	
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- (it can be selected randomly or based on some information).
- **S1.** Compute the distance $d_0 = d(P, x)$ where x is a new test pattern.

S2. If $d_0 \leq \delta$, where δ is a user defined threshold, then

assign the label 'normal" to x otherwise, report a network intrusion.

4. Experimental results and discussion

4.1 Data set description

The principle interest of this work is to benchmark the performance of the proposed model by using KDD Cup1999 Data Set [46] which is generally recognized and widely used by researchers working on IDS field. The main task for the KDD 99 classifier learning contest was to provide a predictive model able to distinguish between normal and intrusion or attacks connections in a computer network. KDD training dataset includes approximately 4,900,000 single connection records each of which contains 41 features and is labeled as either normal or an attack, with exactly one specific attack type. The simulated attacks fall in one of the following four categories: DOS (denial of service attacks), R2L (remote user unauthorized access to the local), U2R (illegal access to super-privilege attacks) and Probing (surveillance and other probing attacks). In our experiment we have used about 1,000,000 of the data and we have labeled all the data as being either normal or abnormal. The distribution of the data is shown in table 1.

Data type	Normal	Attack	
Number of data	595795	452778	

4.2 Accuracy Measure

Estimating classifier accuracy is important in that it allows one to evaluate how accurately a given classifier will label the test data. To evaluate the effectiveness of a classifier for problems with skewed classes, the standard precision, recall, specificity, F_1 measure and total accuracy are used here. The evaluation measures which are used in approach for testing process in our research work could be defined as follows [47]:

- *True Positive (TP):* This states the number of normal connection records correctly classified as normal.
- True Negative (TN): This states the number of attack records correctly classified as attack.
- False Positive (FP): This states the number of normal records classified as attack.

False Negative (FN): This states the number of attack records classified as normal.

In a classification task, the precision for a class is defined to be the ratio of true positives divided by the total number of elements labeled as belonging to the positive class. Recall is the ratio of true positives divided by the total number of elements that actually belong to the positive class. Specificity is the percentage of negative labeled instances that were predicted as negative. The F_1 measure tries to balance both precision and recall indeed, it is the harmonic mean between precision and recall. Finally accuracy indicates the percentage of predictions that were correct. The precision, recall, specificity, F_1 measure and accuracy are respectively defined in the following form:

$$precision = \frac{TP}{TP + Fp}$$
(4)

$$recall = \frac{TP}{TP + FN}$$
(5)

$$specificity = \frac{TN}{TN + FP}$$
(6)

$$F_1 = 2 \times \frac{\text{precision} \times \text{recall}}{\text{precision} + \text{recall}}$$
(7)

$$accuracy = \frac{Tp + TN}{TP + TN + FP + FN}$$
(8)

4.3 Results

In this section we detail the overall results of the proposed framework. In Figure 1(a) and (b), the precision, recall and specificity of the proposed method and conventional *k*-*NN* are depicted. We can see that both models have the same behavior as the values of threshold parameter δ change. Larger values of δ lead to low recall and higher precision and specificity while smaller values for that result in higher recall and lower precision and specificity.

It should be mentioned that under the anomaly detection perspective, recall should be as high as possible, but precision and specificity should also be high. Indeed for the sake of optimization recall, precision and specificity must be kept in equilibrium. Figure 2 shows the relation between recall, precision and specificity for the conventional *k*-*NN* and our proposed model.



Figure 2. Relation between recall, precision and specificity (a) K-NN (b) Proposed Model

In order to evaluate the performance of the proposed method more accurately F1 measure which takes into account both precision and recall and classification accuracy are considered. Tables 2 and 3 show the comparison of the experimental results of the proposed model endowed with different positive valuation functions [42, 43] with those of produced by the conventional *K-NN* and fuzzy *K-NN* algorithms for different values of threshold parameter δ . In this work the proposed method endowed with linear valuation function v(x) = x, nonlinear valuation functions $v(x) = \frac{1}{1 + e^{-x}}$, $v(x) = \arctan(x)$ and $v(x) = \sin(x)$ are denoted respectively by *LBK-NN_x*, *LBK-NN_e*, *LBK-NN_a* and *LBK-NN_s* where, *LBK-NN* stands for Lattice Based *K-NN*.

For each algorithm 10 best results are reported for different values of parameter δ raised in steps of 0.0002

Note that depending on the algorithm the values of parameter δ lies in different intervals.

Conventional K-NN		Fuzzy K-NN			LBK-NN _x			
Threshold	F₁ measure	Accuracy	Threshold	F₁ measure	Accuracy	Threshold	F ₁ measure	Accuracy
0.0544	0.9767	0.9739	0.9468	0.9775	0.9758	0.1460	0.9795	0.9770
0.0546	0.9773	0.9743	0.9470	0.9784	0.9757	0.1462	0.9795	0.9770
0.0548	0.9773	0.9744	0.9472	0.9782	0.9756	0.1464	0.9795	0.9770
0.0550	0.9775	0.9747	0.9474	0.9780	0.9753	0.1466	0.9796	0.9770
0.0552	0.9779	0.9752	0.9476	0.9780	0.9752	0.1468	0.9796	0.9770
0.0554	0.9780	0.9753	0.9478	0.9775	0.9748	0.1470	0.9796	0.9769
0.0556	0.9782	0.9755	0.9480	0.9784	0.9746	0.1472	0.9796	0.9770
0.0558	0.9783	0.9756	0.9482	0.9772	0.9744	0.1474	0.9795	0.9770
0.0560	0.9784	0.9757	0.9484	0.9768	0.9740	0.1476	0.9795	0.9769
0.0562	0.9785	0.9758	0.9486	0.9763	0.9733	0.1478	0.9795	0.9770

Table 2. Different measures used to evaluate the performance of the methods.

LBK-NN _e			LBK-NNa			LBK-NNs		
Threshold	F₁ measure	Accuracy	Threshold	F₁ measure	Accuracy	Threshold	F₁ measure	Accuracy
0.0762	0.9794	0.9770	0.0376	0.9798	0.9772	0.1522	0.9815	0.9788
0.0764	0.9795	0.9770	0.0378	0.9796	0.9772	0.1524	0.9816	0.9790
0.0766	0.9795	0.9771	0.0380	0.9798	0.9773	0.1526	0.9819	0.9791
0.0768	0.9799	0.9774	0.0382	0.9800	0.9773	0.1528	0.9818	0.9792
0.0770	0.9798	0.9774	0.0384	0.9799	0.9773	0.1530	0.9819	0.9793
0.0772	0.9799	0.9774	0.0386	0.9799	0.9773	0.1532	0.9820	0.9794
0.0774	0.9801	0.9775	0.0388	0.9799	0.9773	0.1534	0.9820	0.9794
0.0776	0.9799	0.9776	0.0390	0.9798	0.9773	0.1536	0.9822	0.9795
0.0778	0.9799	0.9775	0.0392	0.9798	0.9772	0.1538	0.9822	0.9796
0.0780	0.9796	0.9774	0.0394	0.9789	0.9764	0.1540	0.9822	0.9796

Table 3. Different measures used to evaluate the performance of the methods.

In Table 3, the minimum, maximum and average for the classification accuracy and F_1 measure on the entire experiments have been shown. In other words first, the minimum, maximum and average of each column of the Tables 1 and 2 have been calculated, and then the results for the algorithm with better performance have been shown in bold. As it can be seen, the *LBK-NN*_s algorithm in all cases has achieved better results and outperforms other methods.

Algorithm\Measure	F ₁ Measure	l.		Accuracy			
	Min	Average	Max	Min	Average	Max	
Conventional K-NN	0.9767	0.9778	0.9785	0.9739	0.9750	0.9758	
Fuzzy <i>K-NN</i>	0.9763	0.9776	0.9784	0.9733	0.9749	0.9758	
LBK-NN _x	0.9795	0.9795	0.9796	0.9769	0.9770	0.9770	
LBK-NN _e	0.9794	0.9798	0.9801	0.9770	0.9773	0.9776	
LBK-NN _a	0.9789	0.9797	0.9800	0.9764	0.9772	0.9773	
LBK-NN _s	0.9815	0.9819	0.9822	0.9788	0.9793	0.9796	

Table 3. The performance of the models

5. Conclusion

This study proposed a nearest neighbor classifier based on lattice theory capable of detecting large-scale attacks in real-time. Experimental results on the well-known KDD Cup 1999 data set demonstrate that the proposed method can effectively detect anomalies with high detection rate. Furthermore the performance of the proposed model can be improved by tuning valuation function v. The inherent speed of the algorithm for training is another advantage of the algorithm.

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